





### Introduction

- In this topic, we will
  - Describe approximating  $A\mathbf{u} = \mathbf{v}$  when no exact solution exists
  - Introduce the normal equation
  - Use the normal equation to find the
    - Best-fitting linear polynomial that fits noisy data
    - Best-fitting quadratic polynomial that fits noisy data





- From linear algebra:
  - Suppose that  $A: \mathbb{R}^2 \to \mathbb{R}^4$  and  $A\mathbf{u} = \mathbf{v}$  has no solution
  - If the columns of A are linearly independent,
     this requires that the system is overdetermined with rank 3
    - That is, there are more equations than unknowns and the system is inconsistent

$$\begin{pmatrix} 3.1 & 4.0 \\ 2.8 & 7.6 \\ 5.9 & 1.2 \\ 6.4 & 8.7 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} 5.6 \\ 0.8 \\ 7.3 \\ 9.1 \end{pmatrix}$$





- Thus, there is no linear combination of the columns of *A* that equals the target vector
  - Thus, for all  $u_1$  and  $u_2$ ,

$$u_{1} \begin{pmatrix} 3.1 \\ 2.8 \\ 5.9 \\ 6.4 \end{pmatrix} + u_{2} \begin{pmatrix} 4.0 \\ 7.6 \\ 1.2 \\ 8.7 \end{pmatrix} \neq \begin{pmatrix} 5.6 \\ 0.8 \\ 7.3 \\ 9.1 \end{pmatrix}$$

- What's the next-best choice?
  - How about, what linear combination is closest to v?





- Let  $A: \mathcal{U} \rightarrow \mathcal{V}$  be a linear map
  - Usually,  $A: \mathbf{R}^n \to \mathbf{R}^m$
- Thus, we want to minimize  $\|A\mathbf{u} \mathbf{v}\|_2$ 
  - That is, find a u that makes this as small as possible
  - Now, consider a plane (e.g., a floor) and a point not on that plane
    - The location on the plane closest to the point is one that forms a perpendicular vertical line
  - We need to find a vector  $\mathbf{u}_0$  such that  $A\mathbf{u}_0 \mathbf{v}$  is perpendicular to all vectors in the range of  $A\mathbf{u}$ 
    - Two vectors are perpendicular if their dot product is zero





Thus, we require that

$$(A\mathbf{u}_0 - \mathbf{v}) \cdot A\mathbf{u} = 0$$

for all  $\mathbf{u}$  in the domain  $\mathbf{R}^n$ 

$$\mathbf{v} \cdot (A\mathbf{u}) = (A^{\mathsf{T}}\mathbf{v}) \cdot \mathbf{u}$$

If this is true, then

$$A^{\mathsf{T}} \left( A \mathbf{u}_0 - \mathbf{v} \right) \cdot \mathbf{u} = 0$$

must be true for all  $\mathbf{u}$  in  $\mathbf{R}^n$ 

This is true if and only if

$$A^{T} (A\mathbf{u}_{0} - \mathbf{v}) = \mathbf{0}$$

$$A^{T} A\mathbf{u}_{0} - A^{T} \mathbf{v} = \mathbf{0}$$

$$A^{T} A\mathbf{u}_{0} = A^{T} \mathbf{v}$$

$$\mathbf{u}_{0} = (A^{T} A)^{-1} A^{T} \mathbf{v}$$





Therefore, the solution to

$$A^{\mathsf{T}} A \mathbf{u}_0 = A^{\mathsf{T}} \mathbf{v}$$

which may sometimes be calculated as

$$\mathbf{u}_0 = \left(A^{\mathrm{T}}A\right)^{-1}A^{\mathrm{T}}\mathbf{v}$$

is that vector  $\mathbf{u}_0$  that minimizes

$$\|A\mathbf{u}_0 - \mathbf{v}\|_2$$





Let's try this out:

```
\Rightarrow A = [3.1 4.0; 2.8 7.6; 5.9 1.2; 6.4 8.7];
>> v = [5.6 0.8 7.3 9.1]';
\Rightarrow u = (A'*A) \ A'*v
    u =
        1.472633619403234
       -0.169731501459659
>> A*u
    ans =
        3.886238214311391
        2.833414723235649
        8.484860552727493
        7.948191101481669
>> norm( A*u - v )
    ans =
        3.130864603088711
```

```
3.886238214311391
2.833414723235649
8.484860552727493
7.948191101481669
```





- Suppose we have some data points
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     If there were only two points, we could solve  $\begin{pmatrix} x_1 & 1 \\ x_2 & 1 \end{pmatrix} \begin{pmatrix} a_1 \\ a_0 \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$
  - Now, however, we have five:

$$\begin{pmatrix}
x_1 & 1 \\
x_2 & 1 \\
x_3 & 1 \\
x_4 & 1 \\
x_5 & 1
\end{pmatrix}
\begin{pmatrix}
a_1 \\
a_0
\end{pmatrix} = \begin{pmatrix}
y_1 \\
y_2 \\
y_3 \\
y_4 \\
y_5
\end{pmatrix}$$

$$y_2 \\
y_4 \\
y_5$$

$$y_3 \\
y_4 \\
y_5$$

$$y_4 \\
y_5$$

$$y_4 \\
y_1 \\
\vdots \\
x_1 \quad x_2 \quad x_3$$

$$x_4 x_5$$





- We can thus as:
  - What linear combination  $a_1$

our target vector 
$$\mathbf{y} = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \\ y_5 \end{pmatrix}$$

comes closest to







• *y*<sub>5</sub>

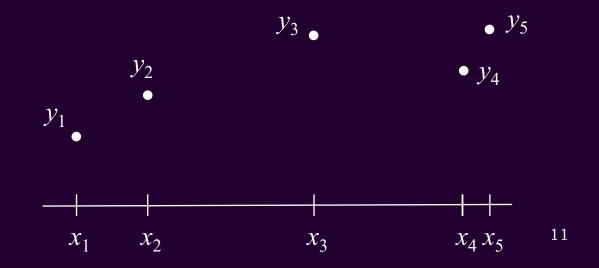




We have already seen the solution:

- Solve 
$$A^{T}A\mathbf{a} = A^{T}\mathbf{y}$$

$$\begin{pmatrix} x_{1} & x_{2} & x_{3} & x_{4} & x_{5} \\ 1 & 1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} x_{1} & 1 \\ x_{2} & 1 \\ x_{3} & 1 \\ x_{4} & 1 \\ x_{5} & 1 \end{pmatrix} \begin{pmatrix} a_{1} \\ a_{0} \end{pmatrix} = \begin{pmatrix} x_{1} & x_{2} & x_{3} & x_{4} & x_{5} \\ 1 & 1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} y_{1} \\ y_{2} \\ y_{3} \\ y_{4} \\ y_{5} \end{pmatrix}$$

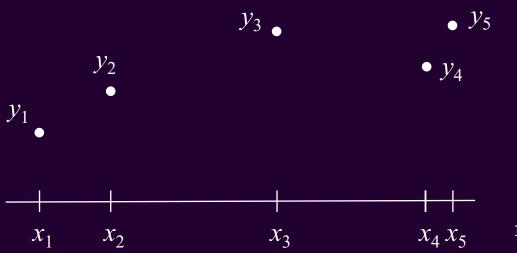






- We have already seen the solution:
  - Solve  $A^{\mathrm{T}}A\mathbf{a} = A^{\mathrm{T}}\mathbf{y}$

$$\begin{pmatrix}
\sum_{k=1}^{n} x_k^2 & \sum_{k=1}^{n} x_k \\
\sum_{k=1}^{n} x_k & n
\end{pmatrix}
\begin{pmatrix}
a_1 \\
a_0
\end{pmatrix} =
\begin{pmatrix}
\sum_{k=1}^{n} x_k y_k \\
\sum_{k=1}^{n} y_k
\end{pmatrix}$$

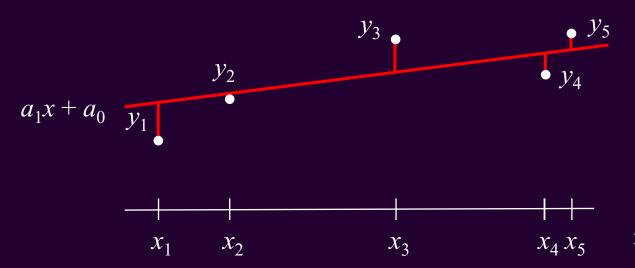






- The solution gives us the best-fitting line
  - The sum of the squares of the errors is minimized

$$\begin{pmatrix} \sum_{k=1}^{n} x_k^2 & \sum_{k=1}^{n} x_k \\ \sum_{k=1}^{n} x_k & n \end{pmatrix} \begin{pmatrix} a_1 \\ a_0 \end{pmatrix} = \begin{pmatrix} \sum_{k=1}^{n} x_k y_k \\ \sum_{k=1}^{n} y_k \end{pmatrix}$$



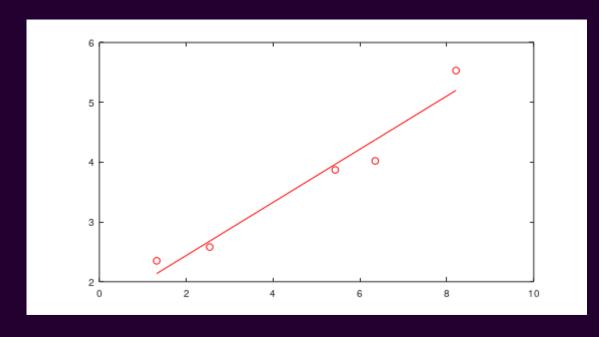




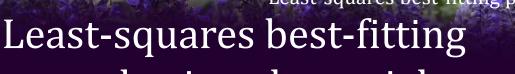
## Example

Let's try this in MATLAB

```
>> x = [1.32 \ 2.54 \ 5.43 \ 6.35 \ 8.21]';
\Rightarrow y = [2.35 2.58 3.87 4.02 5.53]';
>> plot( x, y, 'ro' )
\Rightarrow A = vander(x, 2)
    A =
        1.3200
                 1.0000
        2.5400 1.0000
        5.4300 1.0000
        6.3500 1.0000
        8.2100
                  1.0000
>> format long
\Rightarrow a = (A'*A) \ (A'*y)
    a =
        0.444616162573875
        1.549180904522615
```







- quadratic polynomial
- Suppose we have some data points

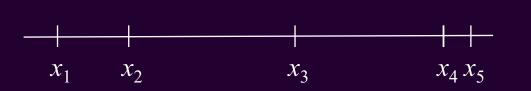
$$\begin{pmatrix} x_1^2 & x_1 & 1 \\ x_2^2 & x_2 & 1 \\ x_3^2 & x_3 & 1 \\ x_4^2 & x_4 & 1 \\ x_5^2 & x_5 & 1 \end{pmatrix} \begin{pmatrix} a_2 \\ a_1 \\ a_0 \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \\ y_5 \end{pmatrix} \quad y_3$$

Suppose we have some data points

- If there were three points, we could solve

- Now, however, we have five:

$$\begin{pmatrix}
x_1^2 & x_1 & 1 \\
x_2^2 & x_2 & 1 \\
x_3^2 & x_3 & 1
\end{pmatrix}
\begin{pmatrix}
a_2 \\
a_1 \\
a_0
\end{pmatrix} = \begin{pmatrix}
y_1 \\
y_2 \\
y_3
\end{pmatrix}$$



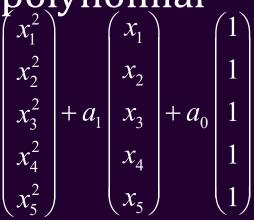




# Least-squares best-fitting quadratic polynomial

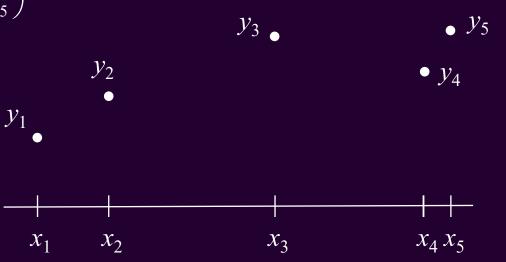
- We can thus as:
  - What linear combination  $a_2$

closest to 
$$\mathbf{y} = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \\ y_5 \end{pmatrix}$$



comes

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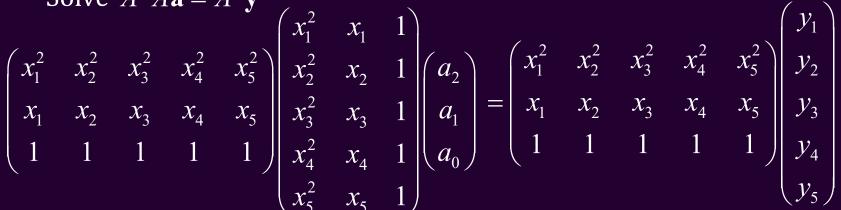


# Least-squares best-fitting quadratic polynomial

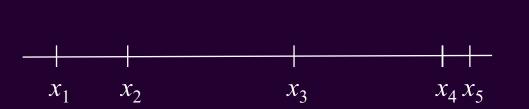
- As before, we can solve this:
  - Solve  $A^{\mathrm{T}} A \mathbf{a} = A^{\mathrm{T}} \mathbf{y}$

$$\begin{pmatrix} x_1^2 & x_2^2 & x_3^2 & x_4^2 & x_5^2 \\ x_1 & x_2 & x_3 & x_4 & x_5 \\ 1 & 1 & 1 & 1 & 1 \end{pmatrix}$$

$$\begin{pmatrix}
x_1^2 & x_1 & 1 \\
x_2^2 & x_2 & 1 \\
x_3^2 & x_3 & 1 \\
x_4^2 & x_4 & 1 \\
x_5^2 & x_5 & 1
\end{pmatrix}$$











# Least-squares best-fitting quadratic polynomial

- As before, we can solve this:
  - Solve  $A^{\mathrm{T}}A\mathbf{a} = A^{\mathrm{T}}\mathbf{y}$

$$\begin{pmatrix}
\sum_{k=1}^{n} x_{k}^{4} & \sum_{k=1}^{n} x_{k}^{3} & \sum_{k=1}^{n} x_{k}^{2} \\
\sum_{k=1}^{n} x_{k}^{3} & \sum_{k=1}^{n} x_{k}^{2} & \sum_{k=1}^{n} x_{k} \\
\sum_{k=1}^{n} x_{k}^{2} & \sum_{k=1}^{n} x_{k} & n
\end{pmatrix}
\begin{pmatrix}
a_{2} \\
a_{1} \\
a_{0}
\end{pmatrix} = \begin{pmatrix}
\sum_{k=1}^{n} x_{k}^{2} y_{k} \\
\sum_{k=1}^{n} x_{k} y_{k} \\
\sum_{k=1}^{n} y_{k}
\end{pmatrix}$$

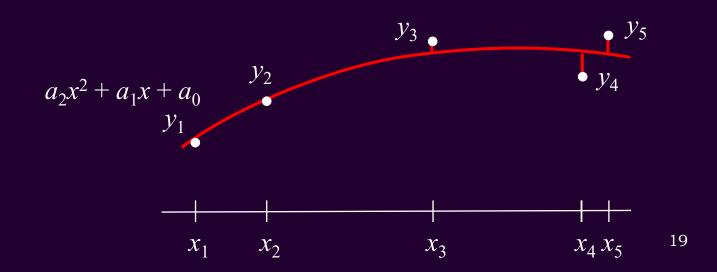
$$y_{2} \qquad y_{4}$$





# Least-squares best-fitting quadratic polynomial

- The solution gives us a quadratic polynomial that most closely approximates these points
  - The sum of the squares of the errors is minimized



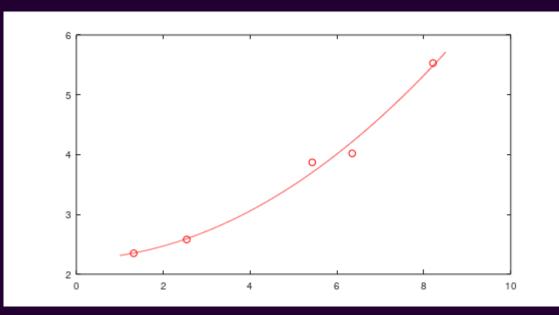




## Example

Let's try this in MATLAB

```
\Rightarrow x = [1.32 2.54 5.43 6.35 8.21]';
y = [2.35 \ 2.58 \ 3.87 \ 4.02 \ 5.53]';
>> plot( x, y, 'ro' )
\Rightarrow A = vander(x, 3)
    A =
      1.7424
               1.32 1
      6.4516 2.54 1
     29.4849 5.43 1
     40.3225 6.35 1
     67.4041 8.21
>> format long
\Rightarrow a = (A'*A) \ (A'*y)
    a =
        0.04547642859987164
        0.02113915928445630
        2.246661642457417
>> hold on
\Rightarrow xs = 1:0.01:8.5;
```



>> plot( xs, polyval( a, xs ), 'r' );





## Example

 Incidentally, in MATLAB if you try to solve an overdetermined system of linear equations, it automatically gives you the leastsquares best-fitting solution:

```
>> a = (A'*A) \ (A'*y)
    a =
        0.04547642859987164
        0.02113915928445630
        2.246661642457417
>> a = A \ y
        a =
        0.04547642859987018
        0.02113915928447047
        2.246661642457392
```

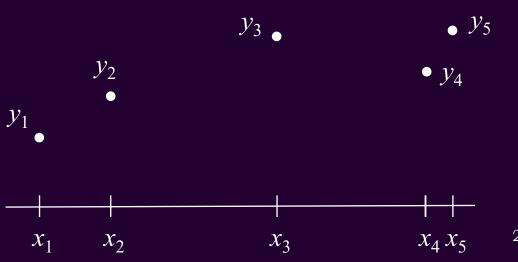




# Least-squares best-fitting constant polynomial

• What is the best constant polynomial  $y = a_0$  passing through data?

$$\begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} (a_0) = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} 1 \quad 1 \quad 1 \quad 1 \quad 1 \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \\ y_5 \end{pmatrix}$$





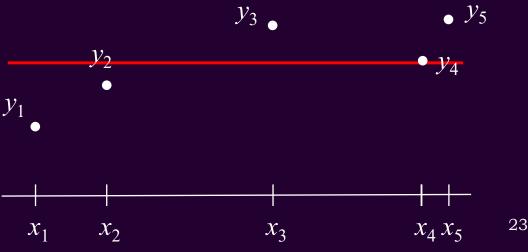


# Least-squares best-fitting constant polynomial

What is the best constant polynomial  $y = a_0$  passing through data?

$$(n)(a_0) = \left(\sum_{k=1}^n y_k\right)$$

- The solution is  $a_0 = \frac{1}{n} \sum_{k=1}^{n} y_k$ 







## Summary

- Following this topic, you now
  - Understand the idea of finding the solution such that Au is closest to a target vector v
  - Know that this requires you to solve  $A^{T}A\mathbf{u} = A^{T}\mathbf{v}$
  - Understand that this can be used to find least-squares best-fitting polynomials passing through data
    - We can find a least-squares constant polynomial, least-squares linear polynomial, least-squares quadratic polynomial and others





## References

[1] https://en.wikipedia.org/wiki/Least\_squares





# Acknowledgments

None so far.





# Colophon

These slides were prepared using the Cambria typeface. Mathematical equations use Times New Roman, and source code is presented using Consolas. Mathematical equations are prepared in MathType by Design Science, Inc. Examples may be formulated and checked using Maple by Maplesoft, Inc.

The photographs of flowers and a monarch butter appearing on the title slide and accenting the top of each other slide were taken at the Royal Botanical Gardens in October of 2017 by Douglas Wilhelm Harder. Please see

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